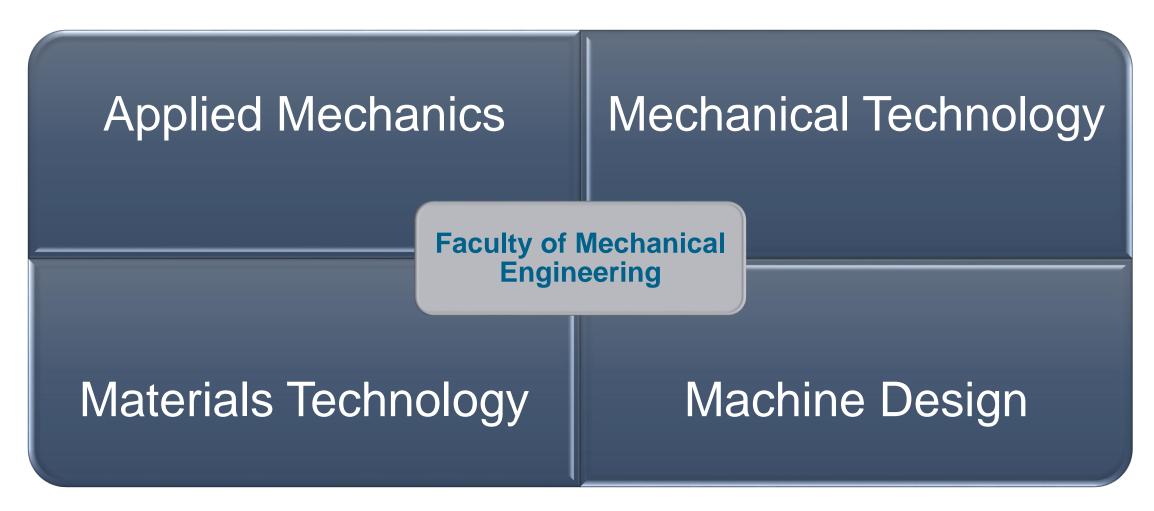




Faculty of Mechanical Engineering Institutes



Institute of Machine Design



research workstation with hydraulic and pneumatic systems



image recording and analysis station equipped with a fast Cronos 1.4 camera and a lighting system

Institute of Applied Mechanics





















Laboratory of Strength of Materials and Structures

Laboratory of Vibration & Machine Dynamics



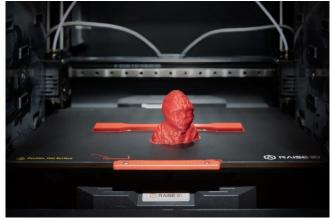
Institute of Applied Mechanics





3D Cube Pro





XYZprinting da Vinci
1.0 Pro

Nobel 1.0 Advanced SLA



Laboratory of Rapid Prototyping



Institute of Mechanical Technology





Machining Laboratory









Laboratory of Coordinate Metrology

Institute of Mechanical Technology

Specialized software for programming and simulating the work of robotic stations in offline mode:

- RobotStudio,
- RoboGuide,
- DTPS-G2PCTool,

	ABB	ABB	FANUC	PANASONIC
type	IRB 140T	FlexPicker 360	M16iB-10L	TA-1400
degrees of freedom	6	3/4	6	6
lifting capacity [kg]	6	1/3	10	6
robot repeatability [mm]	0,03	0,1	0,1	0,1
robot mass [kg]	98	120	230	161
control system	IRC5	IRC	R30iA	G2

enable programming of manipulation and technological robots, e.g. welding and designing robotic stations and simulating their work in a virtual environment.

Laboratory of Robotization of Production processes

Institute of Materials Technology







Plastics Laboratory

Institute of Materials Technology



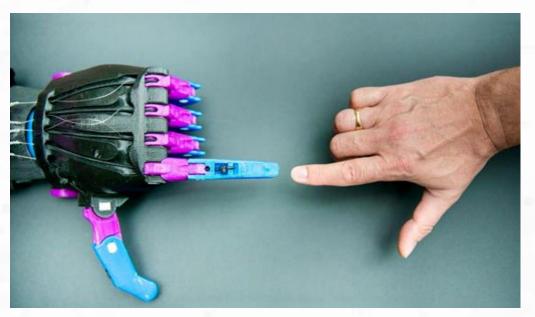
VR & AR Laboratory

Rapid Prototyping Laboratory



EMERALD - European network for 3D printing of biomimetic mechatronic systems

KICKOFF MEETING - CLUJ NAPOCA - 28.02.2022



Filip GÓRSKI, DSc, PhD, BEng Associate Professor at Poznan University of Technology filip.gorski@put.poznan.pl filip.gorski.employee.put.poznan.pl











POZNAN UNIVERSITY OF TECHNOLOGY EMERALD TEAM

Team leader:

Filip GÓRSKI, DSc, PhD, BEng, Associate Professor, VR & 3D printing head

Team members:

Remigiusz ŁABUDZKI, PhD, BEng Radosław WICHNIAREK, PhD, BEng Dominik RYBARCZYK, PhD, BEng Roman REGULSKI, MSc, BEng Magdalena ŻUKOWSKA, MSc, BEng Justyna RYBARCZYK, MSc, BEng

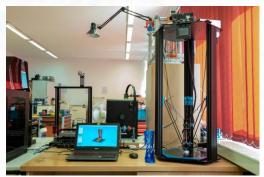
Faculty of Mechanical Engineering Institute of Materials Technology Institute of Mechanical Technology



POZNAN UNIVERSITY OF TECHNOLOGY EMERALD TEAM

Team skills:

- CAD/CAM/CAE, design automation,
- medical data processing,
- anatomical & medical design (prostheses, orthoses, implants...)
- 3d scanning, reverse engineering, mesh processing,
- 3d printing in FDM and SLA, Vacuum Casting,
- robot programming, PLC, vision systems,
- Virtual/Augmented/Mixed Reality systems development









Available laboratories:

- Rapid Manufacturing
- Virtual Reality
- Mechatronics
- Measurement Systems



EXPERIENCE IN PREVIOUS PROJECTS EXAMPLES

1) AutoMedPrint – Automation of design and rapid manufacturing of orthopedical and prosthetic supplies by anatomical measurement, automedprint.put.poznan.pl R&D project

2) BRIGHT

Boosting the scientific excellence and innovation capacity of 3D printing methods in pandemic period, bright-project.eu *Erasmus+*

3) ErgoDesign

Improving digital skills for Ergonomics and Bioengineering Innovations for inclusive Health Care Erasmus+



EXPERIENCE IN PREVIOUS PROJECTS



















EMERALD INTELLECTUAL OUTPUT 4

Title: EMERALD e-case studies for project based learning method used in developing, testing and manufacturing of new biomimetic mechatronic systems by 3D printing technologies

Aim: implementation of the communication and dissemination strategy - creating case study reports and publications

Main assumptions/deliverables:

- 4 case studies of biomimetic mechatronic systems made by 3D printing for people with special needs
- 3 different teams, 5-7 students from different countries, realization of the complete process (CAD->CAE->printing->programming->assembly)
- 4 case study reports
- 1 open access book
- 1 open access toolkit manual
- 4 academic papers (ISI, IF)

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Time period: 15.02.2022 - 29.09.2023 (whole project!)

EMERALD INTELLECTUAL OUTPUT 4

Plan of conduct and responsibilities - full scale

- 0. Management and overall work distribution PUT
- 1. Selection and medical description of cases (1 case = 1 person with special need, e.g. an amputee) <u>PUT</u>
- 2. Measurement, anatomical digitization, data processing PUT
- 3. Design of devices mechanical part PUT
- 4. Material selection University of Bucharest
- 5. Design of devices electronics & drive Agder/Bizzcom/PUT
- 6. VR/AR visualization BizzCom
- 7. CAE analysis TUCN
- 8. 3D printing, post processing all eligible partners
- 9. Assembly, programming Agder/Bizzcom/PUT
- 10. Testing with patients, feedback PUT
- 11. Preparing scientific papers all University partners (1 each)!
- 12. Preparing toolkit manual PUT + partner contributions
- 13. Preparing open access book all partners



THANK YOU FOR YOUR ATTENTION!









